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A CHARACTERIZATION OF “PHELPSIAN” STATISTICAL DISCRIMINATION

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Abstract

We establish that statistical discrimination is possible if and only if it is impossible to uniquely identify the signal structure observed by an employer from a realized empirical distribution of skills. The impossibility of statistical discrimination is shown to be equivalent to the existence of a fair, skill-dependent remuneration for every set of tasks every signal-dependent optimal assignment of workers to tasks. Finally, we connect this literature to Bayesian persuasion, establishing that if the possibility of discrimination is absent, then the optimal signalling problem results in a linear payoff function (as well as a kind of converse).

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1 Introduction

In seminal contributions, Arrow (1971; 1973) and Phelps (1972) postulated that discrimination along racial lines, or gender identities, can have a statistical explanation. In this note we focus on Phelps’ notion of statistical discrimination: on the idea that two agents who are in essence identical may have different economic remunerations for purely informational reasons.¹

Phelps’ theory assumes a firm who observes a signal about the underlying skills of a worker. The firm observes the signal before assigning the worker a task. The worker is paid her expected contribution to the firm, conditional on the firm’s observed signal about the worker. (A competitive market ensures that workers are paid their contributions.) Consider now two populations of workers: group A and group B. If the signal is more informative for As than for Bs, then (the argument goes), a worker from group A may be ex-ante more valuable to the firm than a B worker. This is because the additional information about the A worker may be used to better assign her a task matching her skills. Even more, the signal may be the result of a test that has been designed with a population from group A in mind. The signal implemented by the test will then be more informative about the skills of a prospective A worker than a B worker.²

Taking a step back and calculating the expected contribution to the firm of workers drawn from these two populations, the firm may value a group A worker over a group

¹We follow the interpretation of Phelps’ model due to Aigner and Cain (1977). Statistical discrimination stands in contrast with taste-based discrimination, as in Becker (1957).

²As an example, Aigner and Cain cite evidence from the education literature to the effect that the SAT is less informative about the abilities of African-American students than Whites.

B worker simply because it expects to receive better information about the former than about the latter.

We formulate the theory of statistical discrimination using the language of the recent literature on informational design. A firm observes a signal about a worker's skills, and bases both the assigned task and the payment to the worker on the revenues it expects to gain from the action taken by the worker at the firm. We say that discrimination is possible if two distributions of signals inducing the same distributions of skills lead to different expected revenues for the optimizing firm.

Our results are as follows. First, the absence of any possibility of statistical discrimination is shown to be equivalent to a property related to the statistical identification of signals. Specifically, we prove that statistical discrimination is not possible if and only if every given distribution of skills arises from a unique distribution of signals. By definition, when discrimination is possible, the identification property must be violated. Our contribution is in the converse: whenever identification is impossible, discrimination can arise.

We further show that the absence of discrimination is equivalent to the existence of a fair "skill-based" remuneration for workers. Thus, each list of skills must be associated with a value, and every worker is paid the expectation according to her distribution of skills. Finally, we show that the optimal information structure in the sense of Kamenica and Gentzkow (2011) achieves precisely this fair remuneration.

2 The model

2.1 Notation

A set is *binary* if it has one or two elements. If A is a closed subset of a Euclidean space, we denote by $\Delta(A)$ the set of Borel probability measures on A .

2.2 The model

The model involves a firm and a worker. The firm faces uncertainty over the revenues it can obtain from the worker's actions. The revenue depends on the worker's skills, and how those match up with the technology of the firm.

Let Θ denote a set of uncertain *states of the world*; these represent the skill set of the worker that is unknown to the firm. The firm asks the worker to undertake some action, and it only cares about the state-contingent payoff that results from the worker's action. Formally, then, an *action* is an element $a \in \mathbf{R}^\Omega$. Thus, the task of the firm is to properly match a worker to an action with the appropriate skill set.

There is a closed set of *signals*, or *payoff-relevant types*, $\mathcal{S} \subseteq \Delta(\Theta)$. The employer observes $s \in \mathcal{S}$ before asking the employee to undertake an action. Thus, the goal of the firm is to choose the appropriate action for the appropriate employee, after a signal of worker skill has been observed.

The firm solves the following problem. For a given $s \in \mathcal{S}$, and finite set of actions A ,

$$v_A(s) \equiv \max_{a \in A} \sum_{\theta \in \Theta} a(\theta) s(\theta).$$

Given signal $s \in \mathcal{S}$, $v_A(s)$ is the maximal expected revenue the employer can achieve. We maintain the assumption that labor markets are competitive, and therefore a worker of type s is paid the revenues $v_A(s)$ that she generates for the firm. This is as in Phelps (1972) and Aigner and Cain (1977). Observe that v_A is the “value function” of A , as in Blackwell (1953) or Machina (1984), and is thus always convex.

A probability $\pi \in \Delta(\mathcal{S})$ is an *information structure*. It induces a probability over Θ via: $p_\pi(\theta) = \int_{\mathcal{S}} s(\theta) d\pi(s)$. For a set $E \subseteq \mathcal{S}$, we can interpret $\pi(E)$ as an empirical frequency of individuals who generate signals $s \in E$. The empirical frequency π then generates an empirical frequency of skills, which is p_π .

We say that the set of signals \mathcal{S} is *non-discriminatory* if for any information structures $\pi, \pi' \in \Delta(\mathcal{S})$, and any finite set $A \subseteq \mathbf{R}^\Omega$, if $p_\pi = p_{\pi'}$, then

$$\int_{\mathcal{S}} v_A(t) d\pi(t) = \int_{\mathcal{S}} v_A(t) d\pi'(t).$$

Interpret $\pi(E)$ as the frequency of individuals of type $E \subseteq \mathcal{S}$. Under the competitive markets assumption, the set \mathcal{S} being non-discriminatory means that the average remuneration paid to a class of workers with distribution π ultimately depends only on the distribution of their skills.

2.3 Motivation and a Phelpsian example

We start by a simple example to recreate the point made by Phelps (1972). Let $\Theta = \{\theta_1, \theta_2, \theta_3\}$ be the set of states, and $A = \{(1, 0, 0), (0, 1/2, 3)\}$ be the set of available actions. Observe that with this specification, workers are not “high” or “low” quality, but they simply have differing aptitudes for the available actions.

Suppose that

$$\mathcal{S} = \{(1, 0, 0), (1/2, 1/2, 0), (0, 1/2, 1/2), (0, 0, 1)\}$$

is the set of signals, or worker types.

Consider two information structures, π and π' , described in the table below, together with the profit function v_A resulting from our assumed Θ and A :

| | | | | |
|-----------|-----------|---------------|---------------|-----------|
| | (1, 0, 0) | (1/2, 1/2, 0) | (0, 1/2, 1/2) | (0, 0, 1) |
| $\pi(t)$ | 1/3 | 0 | 2/3 | 0 |
| $\pi'(t)$ | 0 | 2/3 | 0 | 1/3 |
| $v_A(t)$ | 1 | 1/2 | 7/4 | 3 |

There are two populations of workers, say A and B. The two populations differ in the information that the firm obtains about their skills. The workers might take a test, as in Phelps (1972), and the informational content of the test might be different for the two populations. So As emit signals about their skills as given by π , while Bs distribution over signals is π' . Observe that $p_\pi = p_{\pi'} = (1/3, 1/3, 1/3)$, reflecting that the populations overall have the same skills.

A worker from group A reveals that she is either good for action $a_1 = (1, 0, 0)$ or action $a_2 = (0, 1/3, 3)$. The B worker reveals the same kind of information, but less efficiently: a signal $t = (1/2, 1/2, 0)$ tells the employer that a_1 is the optimal choice given the information at hand, but leaves the employer with some doubts as to whether a_2 may have been the optimal action. In consequence, we have

$$\int_T v_A(t) d\pi(t) = 1/3 + 7/6 > 1/3 + 1 = \int_T v_A(t) d\pi'(t).$$

If workers are paid according to the revenues that they contribute to the firm, as would be the case in a competitive market, then A workers are paid more than B workers in

aggregate. The differences in expected (or population) remuneration between the two is purely a consequence of the informational content in their corresponding signal structures.

In our example of Phelpsian statistical discrimination, the two different information structures have the same mean. This is a necessary requirement for the existence of statistical discrimination. It is important to point out, however, that skill can *always* be inferred from wages, even when there is discrimination.

In the following, for set of actions $A = \{a_1, \dots, a_n\}$, and action k , let $A + k = \{a_1 + k, \dots, a_n + k\}$.

Proposition 1. *For any \mathcal{S} and any set of actions A , if $\pi, \pi' \in \Delta(\mathcal{S})$ for which $p_\pi \neq p_{\pi'}$, then there is k for which*

$$\int_T v_{A+k}(t) d\pi(t) \neq \int_T v_{A+k}(t) d\pi'(t).$$

2.4 When discrimination is impossible.

Our discussion suggests that discrimination is tied to identification. Skills are always identified from payoffs, even when there is discrimination (Proposition 1). The problem is the converse identification: Here we show that the absence of discrimination is equivalent to the ability to estimate skills from signals. Importantly, we show that this can only happen when payments are linear in signals. So the absence of discrimination is equivalent to the existence of a state-dependent, signal-independent, “fair” payoff. Payments equal the expected value of such a payoff, and are called fair valuations.

We say that \mathcal{S}

- is *identified* if for any $\pi, \pi' \in \Delta(\mathcal{S})$, if $p_\pi = p_{\pi'}$, then $\pi = \pi'$;
- *admits fair valuations* if for any finite subset $A \subseteq \mathbf{R}^\Omega$, there is $\alpha_A \in \mathbf{R}^\Omega$ for which for all $t \in \mathcal{S}$,

$$v_A(t) = \sum_{\theta} \alpha_A(\theta) t(\theta).$$

- *admits fair valuations for binary sets* if for any binary subset $A \subseteq \mathbf{R}^\Omega$, there is $\alpha_A \in \mathbf{R}^\Omega$ for which for all $t \in \mathcal{S}$, $v_A(t) = \sum_{\theta} \alpha_A(\theta) t(\theta)$.

The notion that \mathcal{S} admits fair valuations captures the idea that any individual is paid according to her expected skill. Thus, for A , $\alpha_A(\theta)$ represents the value to the firm of

skill set $\theta \in \Theta$, and if an individual sends signal s then she is paid the expected value of α_A according to s . Importantly, if $\pi \in \Delta(\mathcal{S})$, then

$$\int v_A(s) d\pi(s) = \alpha_A \cdot \int s d\pi(s) = \alpha_A \cdot p_\pi.$$

So the expected payment to a population of agents with information structure π only depends on the distribution of skills in that population.

Finally, say that \mathcal{S} is *non-discriminatory for binary sets* if for any $\pi, \pi' \in \Delta(\mathcal{S})$ and any binary $A \subseteq \mathbf{R}^\Omega$, if $p_\pi = p_{\pi'}$, then

$$\int_{\mathcal{S}} v_A(t) d\pi(t) = \int_{\mathcal{S}} v_A(t) d\pi'(t).$$

Theorem 2. *The following are equivalent.*

1. \mathcal{S} is non-discriminatory.
2. \mathcal{S} is non-discriminatory for binary sets.
3. \mathcal{S} is identified.
4. \mathcal{S} admits fair valuations.
5. \mathcal{S} admits fair valuations for binary sets.

The main import of Theorem 2 is that there is a α_A , independent of the signal s , so that the optimal contribution of the worker to the firm is the expected value of α_A . The worker is therefore remunerated according to some “fundamental” value α_A , and receives the expectation of α_A according to the signal s .

Proposition 3. *If \mathcal{S} admits fair valuations, then for each finite $A \subseteq \mathbf{R}^\Omega$ and corresponding $\alpha_A \in \mathbf{R}^\Omega$, we have for every $s^* \in \mathcal{S}$:*

$$\sum_{\theta} \alpha_A(\theta) s^*(\theta) = \inf \left\{ \sum_{\theta} y(\theta) s^*(\theta) : y \in \mathbf{R}^\Omega \text{ and } v_A(t) \leq \sum_{\theta} y(\theta) s(\theta) \forall s \in \mathcal{S} \right\}.$$

Proposition 3 means that the value of a worker with type s^* to the firm is the minimum expected payment that guarantees the worker a payoff of at least $v_A(s)$, for all signals $s \in \mathcal{S}$. This is a kind of participation, or individual rationality, constraint. The worker may be able to guarantee a payment of $v_A(s)$ on the market, if her signal is s , and thus a firm must guarantee at least $v_A(s)$ in its choice of the “fair” payoff $\alpha_A \in \mathbf{R}^\Omega$.

2.5 Connection to Bayesian persuasion

The recent literature on Bayesian persuasion (Kamenica and Gentzkow (2011)) deals with the optimal design of information structures. It turns out that the value of optimal information design is linear if and only if \mathcal{S} admits no discrimination.

We now focus a bit more in depth on the notion of signal structure. As in Blackwell (1953), there is a natural notion of “comparative informativeness” for $\pi, \pi' \in \Delta(\mathcal{S})$. We say that π is *more informative* than π' if for every A , $\int v_A(t)d\pi(t) \geq \int v_A(t)d\pi'(t)$. Most economists will have heard of the notion of a “mean-preserving spread;” π turns out to be more informative than π' if it consists of a mean-preserving spread of π' .

We know that optimal information design will never utilize signal structures which are dominated according to the more informativeness order. This means that optimal information structures will place probability zero on signals that can be obtained as the mean of other signals. Formally, an optimal information structure will have support on the extreme points of the convex hull of \mathcal{S} .

Now, let T be the closed convex hull of \mathcal{S} . An information structure is any probability measure $\pi \in \Delta(T)$. Then define $W_A : T \rightarrow \mathbf{R}$ via

$$W_A(s) \equiv \max\left\{\int_T v_A(\tilde{s})d\pi(\tilde{s}) : \pi \in \Delta(T) \text{ and } s = \int_T \tilde{s}d\pi(\tilde{s})\right\}.$$

In the following, ∂T refers to the extreme points of T ; those points which are not convex combinations of other points in T .

Return to the motivating example. There, discrimination was present even though \mathcal{S} consisted of the extreme points of its convex hull T , and thus \mathcal{S} was maximally informative. Phelps’ original point can thus be refined: discrimination obtains because an employer has “different” information about two classes of individuals, rather than “better” information.

Let us see how this manifests itself in the choice of optimal information structure. In this case, for each $s \in \mathcal{S}$, we have (clearly) $W_A(s) = v_A(s)$, as each s is extreme in the convex hull of T . We therefore obtain: $(2/3)W_A(1/2, 1/2, 0) + (1/3)W_A(0, 0, 1) = \frac{4}{3} < \frac{3}{2} = (1/3)v_A(1, 0, 0) + (2/3)v_A(0, 1/2, 1/2) \leq W_A(1/3, 1/3, 1/3)$.

Hence, W_A is nonlinear in this case. This is a general artifact of non-identification and discrimination, as is evidenced by the following result.

Proposition 4. *For any \mathcal{S} , ∂T is non-discriminatory iff for every A , W_A is affine (linear).³*

As in Kamenica and Gentzkow (2011), W_A is always weakly concave, which admits the possibility that it is affine. Corollary 4 says that discrimination is possible exactly when W_A exhibits strict concavities.

In general, as each v_A is convex, an information designer choosing an optimal information structure will (weakly) never choose a π putting support on $\mathcal{S} \setminus \partial T$. This is due to the nature of informativeness: any $s \in \mathcal{S} \setminus \partial T$ could be decomposed in a more informative way.

3 Proofs

Let T be the closed convex hull of \mathcal{S} . The set ∂T refers to the extreme points of T . The definition of v_A extends to T . Let $Y_A : T \rightarrow \mathbf{R}$ be the concave envelope of v_A , defined as the pointwise infimum of the affine functions that dominate v_A . So if $\mathcal{A}(T)$ denotes the space of all affine functions on A , then $v_A(t) = \inf\{f(t) : f \in \mathcal{A}(T) \text{ and } v_A \leq f\}$. Recall the definition of W_A from Section 2.5.

Lemma 5. $Y_A = W_A$

Proof. Let $l : T \rightarrow \mathbf{R}$ be an affine function and $v_A \leq l$. For any $\pi \in \Delta(T)$ with $\int_T q d\pi(q) = p$,

$$\int_T v_A(q) d\pi(q) \leq \int_T l(q) d\pi(q) = l\left(\int_T q d\pi(q)\right) = l(p),$$

as l is affine. Thus $W_A \leq l$, as π was arbitrary. This implies that $W_A \leq Y_A$, as l was arbitrary.

Now suppose that $W_A(p) < Y_A(p)$. The set $D = \{(q, y) \in T \times \mathbf{R} : y \leq W_A(q)\}$ is closed and convex, so there exists α with $(q, y) \cdot \alpha \leq (p, W_A(p)) \cdot \alpha < (p, y') \cdot \alpha$ for all $(q, y) \in D$ and all $y' \geq Y_A(p)$. Write $\alpha = (\alpha^1, \alpha^2) \in \mathbf{R}^\Omega \times \mathbf{R}$. Clearly we cannot have $\alpha^2 = 0$ as $(p, W_A(p)) \in D$. Consider the affine function $l : T \rightarrow \mathbf{R}$ defined by

$$q \mapsto (1/\alpha^2)((p, W_A(p)) \cdot \alpha - \alpha^1 \cdot q).$$

³Because the domain of W_A is a set of probability measures, W_A is linear if it is affine.

This means that $l(p) = W_A(p) < Y_A(p)$. Moreover, for any $q \in T$, $\alpha \cdot (q, W_A(q)) \leq (p, W_A(p)) \cdot \alpha$; hence,

$$W_A(q) \leq (1/\alpha^2)\alpha^1 \cdot p + W_A(p) - (1/\alpha^2)\alpha^1 \cdot q = l(q),$$

a contradiction. □

3.1 Proof of Theorem 2

By the Choquet-Meyer Theorem (Theorem II.3.7 in Alfsen (2012) or p. 56-57 in Phelps (2000)), T is a simplex iff ∂T is identified.

Now, to prove the theorem: it is obvious that $3 \implies 1 \implies 2$. We shall prove that $2 \implies 3$. So let \mathcal{S} be non-discriminatory for binary menus.

We prove that $\mathcal{S} = \partial T$ and that T must be a simplex. It is obvious by definition of T that $\partial T \subseteq \mathcal{S}$. So we prove that $\mathcal{S} \subseteq \partial T$. To this end, suppose by means of contradiction that there is $s^* \in \mathcal{S}$ for which there are $t, t' \in T$, $t \neq t'$, and $\gamma \in (0, 1)$ for which $s^* = \gamma t + (1 - \gamma)t'$. Let $f = (s^* - t) + [t \cdot s^* - s^* \cdot s^*]\mathbf{1}$ and $g = -f$. Observe that $f \cdot s^* = 0$, $g \cdot t = -t \cdot (s^* - t) - s^* \cdot (t - s^*) > 0$ and $f \cdot t' = (s^* - t) \cdot (t' - s^*) = \gamma(1 - \gamma)(t' - s^*) \cdot (t' - s^*) > 0$.

Let $A \equiv \{f, g\}$. Then we obtain that $v_A(t) \geq g \cdot t > 0$, $v_A(t') \geq f \cdot t' > 0$, while $v_A(s^*) = 0$ (as $f \cdot s^* = g \cdot s^* = 0$).

Now, for each of t, t' , there are finitely supported (by Caratheodory's theorem) π_t and $\pi_{t'}$ on ∂T (so in particular on \mathcal{S}) for which $t = \int_{\mathcal{S}} s d\pi(s)$ and $t' = \int_{\mathcal{S}} s d\pi'(s)$. This means that $\int_{\mathcal{S}} v_A(s) d\pi(s) \geq v_A(t) > 0$ and $\int_{\mathcal{S}} v_A(s) d\pi'(s) \geq v_A(t') > 0$, as v_A is convex. Then

$$\int_{\mathcal{S}} v_A(s) d(\gamma\pi + (1 - \gamma)\pi')(s) > 0.$$

But this contradicts 2 as $\int_{\mathcal{S}} s d(\gamma\pi + (1 - \gamma)\pi')(s) = \gamma t + (1 - \gamma)t' = s^*$ and $v_A(s^*) = 0$.

So we have shown that $\mathcal{S} = \partial T$. By Alfsen (2012) Theorem II.4.1, since T is convex and compact, T is a simplex (and thus \mathcal{S} identified) if and only if $\mathcal{A}(T)$ forms a lattice in the usual (pointwise) ordering on functions. So, suppose by means of contradiction that $\mathcal{A}(T)$ does not form a lattice. Then, there are $f, g \in \mathcal{A}(T)$ which possess no supremum in $\mathcal{A}(T)$.

Lemma 6. *Let $f, g \in \mathcal{A}(T)$. For any $z \in \partial T$, if $f(z) \geq g(z)$, then there is $h \in \mathcal{A}(T)$ for which $h \geq f, g$ and $h(z) = f(z)$.*

Proof. Let M be the subgraph of the concave envelope of $v_{\{f, g\}}$. Observe by definition that it is the convex hull of the points $\{(z, v_{\{f, g\}}) : z \in \mathcal{S}\}$, so that it is polyhedral (Corollary 19.1.2 of Rockafellar (1970)). Therefore, by definition of polyhedral concave function, there is h supporting it at $(z, f(z))$. \square

From Lemma 6, and the fact that f and g possess no supremum in $\mathcal{A}(T)$, it follows that there is no affine function h for which for all $z \in \partial T$, $h(z) = \max\{f(z), g(z)\}$. Consequently, if $A \equiv \{f, g\}$, then Y_A is not affine, since for all $z \in \partial T$, it follows that $Y_A(z) = \max\{f(z), g(z)\} = v_A(z)$. Now, Y_A being concave and not affine means that there is $\hat{\pi} \in \Delta(T)$ with $\int_{\mathcal{S}} Y_A(q) d\hat{\pi}(q) < Y_A(p_{\hat{\pi}})$. Since $\mathcal{S} = \partial T$, and Y_A is concave, we can in fact find (by Lemma 4.1 in Phelps (2000)) $\pi \in \Delta(\mathcal{S})$ with $p_{\hat{\pi}} = p_{\pi}$ and

$$\int_{\mathcal{S}} v_A(q) d\pi(q) = \int_{\mathcal{S}} Y_A(q) d\pi(q) \leq \int_{\mathcal{S}} Y_A(q) d\hat{\pi}(q) < Y_A(p_{\hat{\pi}}) = Y_A(p_{\pi}),$$

where the first equality follows from $v_A(q) = Y_A(q)$ for $q \in \mathcal{S}$, and the second inequality from the choice of π .

Now, by Lemma 5, $Y_A(p_{\pi}) = \sup\{\int v_A(q) d\tilde{\pi}(q) : \tilde{\pi} \in \Delta(T) \text{ and } p_{\tilde{\pi}} = p_{\pi}\}$. Then there is $\pi' \in \Delta(\mathcal{S})$ (as the sup is achieved for a measure with support in $\partial T = \mathcal{S}$) with $p_{\pi} = p_{\pi'}$ and $\int_{\mathcal{S}} v_A(q) d\pi(q) < \int_{\mathcal{S}} v_A(q) d\pi'(q)$, contradicting the fact that \mathcal{S} is non-discriminatory for binary menus.

So, we have shown that \mathcal{S} form the vertices of a simplex. This establishes that \mathcal{S} is identified.

Now, we establish the equivalence of 3, 4, and 5. Again, as we already claimed, T is a simplex iff $\mathcal{A}(T)$ is a lattice. First, let us show that if \mathcal{S} admits fair valuations for binary sets, then $\mathcal{A}(T)$ is a lattice. To see this, let $f, g \in \mathcal{A}(T)$. Let $A \equiv \{f, g\}$ and observe that since T is a simplex, there is an affine function α_A such that for each $s \in \mathcal{S}$, we have $\alpha_A \cdot s = \max\{f \cdot s, g \cdot s\}$, since \mathcal{S} admits fair valuations for binary sets. Clearly, for all $t \in T$, $\alpha_A \cdot t \geq \max\{f \cdot t, g \cdot t\}$. Suppose $h \in \mathcal{A}(T)$ with $h \geq f, g$. Let $t \in T$ be arbitrary, and let $\pi \in \Delta(\mathcal{S})$ be such that $p_{\pi} = T$. Then $h(t) = \int_{\mathcal{S}} h(s) d\pi(s) \geq \int_{\mathcal{S}} \alpha_A(s) d\pi(s) = \alpha_A(t)$. So α_A is the join of f, g . So T is a simplex. That $\mathcal{S} = \partial T$ can be proved similarly to the above. So, \mathcal{S} forms the vertices of a simplex, and is hence identified.

Conversely, let us show that if \mathcal{S} is identified, then it admits fair valuations. So, let A be finite. View A as a subset of $\mathcal{A}(T)$. Let $\alpha_A \in \mathcal{A}(T)$ be the join of this finite set. By Lemma 6 and an obvious induction argument, for every $s \in \mathcal{S}$, $\alpha_A \cdot s = \max_{a \in A} a \cdot s = v_A(s)$. So A admits fair valuations.

3.2 Proof of Proposition 3

The Lagrangian for the maximization problem in the definition of W_A is

$$\begin{aligned} L(\pi, \lambda) &= \int_T v_A(t) d\pi(t) + \lambda \cdot \left[p - \int_T q d\pi(q) \right] \\ &= \lambda \cdot p + \int_T (v_A(t) - \lambda \cdot p) d\pi(t) \end{aligned}$$

and apply the maximin theorem (see for example Theorem 6.2.7 in Aubin and Ekeland (2006), which applies here because $\Delta(T)$ is compact).

3.3 Proof of Proposition 1

Observe that for any A and any action l , we have $v_{A+l}(t) = v_A(t) + l \cdot t$. Now, since $p_\pi \neq p_{\pi'}$, there is l for which $l \cdot p_\pi \neq l \cdot p_{\pi'}$. Consequently, there is α for which:

$$\alpha l \cdot (p_\pi - p_{\pi'}) \neq \int_T v_A(t) d\pi'(t) - \int_T v_A(t) d\pi(t).$$

Let $k = \alpha l$, and conclude that:

$$\int_T v_{A+k}(t) d\pi(t) = k \cdot p_\pi + \int_T v_A(t) d\pi(t) \neq k \cdot p_{\pi'} + \int_T v_A(t) d\pi'(t) = \int_T v_{A+k}(t) d\pi'(t).$$

3.4 Proof of Corollary 4

By the Choquet-Meyers Theorem (Theorem II.3.7 in Alfsen (2012)) T is a simplex iff the concave envelope of every lower semicontinuous and convex function is affine. Clearly, when \mathcal{S} is identified, T is a simplex, and since v_A is convex and lower semicontinuous, we obtain that $W_A = Y_A$, the concave envelope. So W_A is affine.

Conversely, suppose that W_A is affine for each finite A . We will show that T is a simplex (so that ∂T forms the vertices of a simplex, and is identified). But this again follows from the fact that W_A is the smallest concave function on T dominating each $a \in A$. Since it is affine, it follows that $\mathcal{A}(T)$ is a lattice, and hence T is a simplex.

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